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1	451	view\$4 same large with (strateg\$4 tree)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:38
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3	13	((view\$4 same large with (strateg\$4 tree)) and navigat\$4 ) and (display\$4 view\$4) with strategies	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:36
4	1	((((view\$4 same large with (strateg\$4 tree)) and navigat\$4 ) and (display\$4 view\$4) with strategies) and condition with path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:37
5	2	(view\$4 same large with (strateg\$4 tree)) and condition with path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:37
6	243	(display\$4 view\$4) same (strateg\$4 tree) and condition near5 path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:40
7	0	((display\$4 view\$4) same (strateg\$4 tree) and condition near5 path ) and (how adj do) and (where adj am adj I)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:41
8	0	((display\$4 view\$4) same (strateg\$4 tree) and condition near5 path ) and ((how adj do) (where adj am adj I))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:41
9	73	((display\$4 view\$4) same (strateg\$4 tree) and condition near5 path ) and navigat\$4 and large	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 13:42
11	24	((((display\$4 view\$4) same (strateg\$4 tree) and condition near5 path ) and navigat\$4 and large) and (portion segment part) with (strateg\$4 tree)) and label	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 14:07
10	44	((((display\$4 view\$4) same (strateg\$4 tree) and condition near5 path ) and navigat\$4 and large) and (portion segment part) with (strateg\$4 tree)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 14:13
12	3870	345/762-767,775-778,815,816,853-855,866;715/514,517-520,512.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 14:16

13	11	345/762-767,775-778,815,816,853-855,866;715/514,517-520,512.ccls. and large with strategies and navigat\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/17 14:18
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[Fast Algorithms for Finding Randomized Strategies in Game.. - Koller, Megiddo, von.. \(1994\)](#) (Correct) (2 citations)

Fast Algorithms for Finding Randomized **Strategies** in Game **Trees** Daphne Koller y  
for Finding Randomized **Strategies** in Game **Trees** Daphne Koller y daphne@cs.berkeley.edu Nimrod  
robotics.stanford.edu/~koller/papers/stoc94.ps

[Prioritization in Parallel Symbolic Computing - Kale, Ramkumar, Saletore, Sinha \(1993\)](#) (Correct) (5 citations)

mechanism of choice for specifying scheduling **strategies**. We demonstrate how priorities can be used in  
search regimes (e.g. state-space search and game **tree** search) and describe how specific priority-based  
nscp.upenn.edu/parallel/environments/charm/papers/Symbolic\_LNCS93.ps.gz

[Identifying peers using a self-contained directory - Aberer, Datta, Hauswirth \(2003\)](#) (Correct)

index structure based on a distributed prefix **tree** that is constructed through a distributed,  
**tree**, i.e. peers are the leaves in this **tree**. **Navigating** a query in this **tree** is done by forwarding 3  
of the queries can also be viewed as routing/**navigating** in a trust graph (similar to the web-of-trust  
www.p-grid.org/Papers/TR-IC-2003-25.pdf

[Highly Scalable Data Balanced Distributed B-trees - Padmashree Krishna \(1995\)](#) (Correct)

In a previous paper [KJ94] we proposed two **strategies** for replication, namely path replication and  
Highly Scalable Data Balanced Distributed B-**trees** Padmashree A. Krishna Theodore Johnson  
ftp.cis.ufl.edu/cis/tech-reports/tr95/tr95-015.ps

[Learning Control Strategies for Object Recognition - Draper \(1996\)](#) (Correct) (9 citations)

1 Learning Control **Strategies** for Object Recognition Bruce A. Draper Dept.  
identify the centroid of the image projection of a **tree**. In both cases, accuracy thresholds would be  
vis-ftp.cs.umass.edu/Papers/draper/svl.ps.gz

[Towards Reliable Autonomous Agents - Simmons \(1995\)](#) (Correct) (2 citations)

during normal operation is readily apparent, and **strategies** for handling exceptions can be developed in  
In particular, TCA maintains a hierarchical task **tree** (Figure 1) that represents the robot's intended  
rover, a wheeled Lunar rover, and an office-**navigation** robot. Introduction Reliability is a key  
www.cs.cmu.edu/afs/cs.cmu.edu/user/reids/www/papers/architectures.ps.gz

[Dynamic Subtrees: a New Data Structure for Manipulating Trees - Xu \(1994\)](#) (Correct)

Subtrees: a New Data Structure for Manipulating **Trees** Ying Xu Informatics Group Engineering Physics  
www.wi.euv-frankfurt-o.de/icci94/papers/a7.ps

[A Polynomial Time Algorithm for Finding Finite Unions.. - Arimura, Shinohara.. \(1993\)](#) (Correct)

Time Algorithm for Finding Finite Unions of **Tree** Pattern Languages Hiroki ARIMURA  
www.i.kyushu-u.ac.jp/~arim/papers/nil91.ps.Z

[An Analytical Approach to File Prefetching - Lei \(1997\)](#) (Correct) (33 citations)

A Study Of Integrated Prefetching And Caching **Strategies**. In Proc. 1995 Acm Sigmetrics, Pages 171-182,  
seeks to build semantic structures, called access **trees**, that capture the correlations between file  
www.mcl.cs.columbia.edu/papers/usenix97.ps.gz

[Timing-Driven Logic Bi-Decomposition - Cortadella \(2003\)](#) (Correct)

logic depth is presented. It combines two **strategies**: logic bi-decomposition of Boolean functions  
logic bi-decomposition of Boolean functions and **tree**-height reduction of Boolean expressions. It is a  
www.lsi.upc.es/~jordic/publications/pdf/tcad03\_bidec.pdf

[Bi-decomposition and tree-height reduction for timing optimization - Cortadella](#) (Correct)

presented. It is based on the combination of two **strategies**: logic bi-decomposition of Boolean functions  
Bi-decomposition and **tree**-height reduction for timing optimization Jordi  
www.lsi.upc.es/~jordic/publications/pdf/iwls02.pdf

Strategic Reflection - Lincoln, Mesequer (1998) (Correct)

capabilities that enable quite sophisticated **strategies** to be expressed very conveniently. Maude's  
[www.logic.tuwien.ac.at/people/gramlich/cade15/lincoln.ps.gz](http://www.logic.tuwien.ac.at/people/gramlich/cade15/lincoln.ps.gz)

Beyond Depth-First: Improving Tabled Logic Programs through.. - Freire (1996) (Correct) (9 citations)

Logic Programs through Alternative Scheduling **Strategies** Juliana Freire Terrance Swift David S. Warren  
are usually modeled by a forest of resolution **trees** containing a **tree** for every tabled subgoal  
[www.cs.sunysb.edu/~tswift/webpapers/pliip-96.ps.gz](http://www.cs.sunysb.edu/~tswift/webpapers/pliip-96.ps.gz)

Co-Evolving Soccer Softbot Team Coordination with Genetic.. - Luke (1997) (Correct) (27 citations)

on those most successful. However, many learning **strategies** (neural networks, decision **trees**, etc.) are  
many learning **strategies** (neural networks, decision **trees**, etc.) are designed not to develop algorithmic  
[www.cs.umd.edu/users/seanl/papers/robocup.ps](http://www.cs.umd.edu/users/seanl/papers/robocup.ps)

Rule-Based Query Optimization, Revisited - Warshaw, Miranker (1999) (Correct) (1 citation)

was gained through built-in rule resolution **strategies** and ad-hoc control constructs. Consequently,  
-each component of the optimizer (operator **tree**, cost-model, rewrite system, and search strategy)  
[www.arlut.utexas.edu/~warshaw/papers/rule-opt99.ps](http://www.arlut.utexas.edu/~warshaw/papers/rule-opt99.ps)

The Complexity of Automated Reasoning - André Vellino (1989) (Correct) (5 citations)

by inadequacies in the basic proof searching **strategies**. The optimistic hope was that better search  
tableaux, linear resolution, the connection method, **tree** resolution and the Davis-Putnam procedure. It is  
[ai.iit.nrc.ca/~andre/Vellino\\_Thesis.ps.gz](http://ai.iit.nrc.ca/~andre/Vellino_Thesis.ps.gz)

Evolving Cooperation Strategies - Haynes, Wainwright, Sen (1994) (Correct) (3 citations)

Evolving Cooperation **Strategies** Thomas Haynes, Roger Wainwright & Sandip Sen  
which can be represented by the corresponding parse **trees**. The leaf nodes of such **trees** are occupied by an  
[www.umsl.edu/~haynes/icmas95.ps](http://www.umsl.edu/~haynes/icmas95.ps)

Normalizing Strategies for Multithreaded Interpretation and.. - Aditya (1995) (Correct) (1 citation)

Normalizing **Strategies** for Multithreaded Interpretation and  
on the Global Heap of Shared Objects **Tree** of Activation Frames f: g: h: loop f: active  
[foothill.lcs.mit.edu:8001/Users/shail/papers/kid-arpa95.ps.Z](http://foothill.lcs.mit.edu:8001/Users/shail/papers/kid-arpa95.ps.Z)

SLIQ: A Fast Scalable Classifier for Data Mining - Mehta, Agrawal, Rissanen (1996) (Correct) (78 citations)

and breadth-first growth is that these **strategies** allow SLIQ to scale for large data sets with no  
of SLIQ 1 a new classifier. SLIQ is a decision **tree** classifier that can handle both numeric and  
[www.almaden.ibm.com/u/ragrawal/papers/edbt96\\_sliq.ps](http://www.almaden.ibm.com/u/ragrawal/papers/edbt96_sliq.ps)

Dynamic Load Balancing of Unstructured Computations in .. - Srivastava, Han.. (1998) (Correct) (1 citation)

Balancing of Unstructured Computations in Decision **Tree** Classifiers A. Srivastava E. Han V. Kumar V.  
[ftp.cise.ufl.edu/pub/faculty/ranka/Proceedings/p9.ps](http://ftp.cise.ufl.edu/pub/faculty/ranka/Proceedings/p9.ps)

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